#### COMP 330: Learning Mixture Models

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# We've Talked A Lot About Some Exmaple Mixture Models

#### But how to learn them?

- $\triangleright$  MLE: standard is EM
- $\triangleright\,$  Bayesian: typically use Gibbs sampling

This lecture: will focuss on GMM learning

Concepts easily extended to other mixtures

#### Gaussian Mixture Modeling

Recall: in GMM, assume data from the following stochastic program:

For 
$$i = 1$$
 to  $n$  **do**:  
 $c_i \sim \text{Categorical}(\pi)$   
 $x_i \sim \text{Normal}(\mu_{c_i}, \Sigma_{c_i})$ 



#### EM for GMM

We won't derive it, but will just describe algorithm Goal is to learn k components over n data points

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Begin by initializing

- $\triangleright$  Choose a set of k points randomly,  $\langle s_1, s_2, ..., s_k \rangle$
- $\triangleright$  Use those to init each  $\mu$ :  $\mu_1 = s_1$ ,  $\mu_2 = s_2$ , etc.
- $\triangleright$  Then set each  $\Sigma$  to be the variance of the data
- ▷ That is, each  $\Sigma_{j,j} = \sum_i \left( \left( \sum_{i'} x_{i',j} / n \right) x_{i,j} \right)^2$
- $\triangleright$  All off-diagonals are zero

#### The E-Step

Compute a "soft" assignment of data to each cluster Simply compute  $Pr[c_i = j | x_i]$  for each i, jFrom Bayes' rule:

$$Pr[c_i = j | x_i] = \frac{f(c_i = j, x_i)}{f(x_i)}$$
$$= \frac{\pi_j \text{Normal}(x_i | \mu_j, \Sigma_j)}{\sum_{j'} \pi_{j'} \text{Normal}(x_i | \mu_{j'}, \Sigma_{j'})}$$

Easy to do in a MapReduce job!

#### The M-Step

First, simply do an MLE for each of the k Gaussians Where each point fractionally contributes to MLE (based on E step) Update for  $\mu_j$ :

$$\mu_j = \frac{\sum_i \Pr[c_i = j | x_i] \times x_i}{\sum_i \Pr[c_i = j | x_i]}$$

Note that each  $x_i$  is a vector!

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Update for  $\sigma_j$ :

$$\sigma_j = \frac{\sum_i \Pr[c_i = j | x_i] \text{outerProd} \left( x_i - \mu_j, x_i - \mu_j \right)}{\sum_i \Pr[c_i = j | x_i]}$$

#### The M-Step

Lastly, update for  $\pi_j$ :

$$\pi_j = \sum_i \Pr[c_i = j | x_i] / n$$

Also easy to do over MapReduce!

#### A Few Caveats

Fails if less than d points have non-zero probability of belonging to a cluster

- $\triangleright$  d is dimensionality of the data
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#### Very sensitive to poor initialization

- $\triangleright$  Typical: run many times, with different initializations
- $\triangleright$  Choose one with highest likelihood

#### Now, Let's Go Bayesian

Recall: Bayesians never estimate parametersThey only estimate variablesEverything has a prior!So this:

For i = 1 to n **do**:  $c_i \sim \text{Categorical}(\pi)$  $x_i \sim \text{Normal}(\mu_{c_i}, \Sigma_{c_i})$ 

#### Now, Let's Go Bayesian

Recall: Bayesians never estimate parametersThey only estimate variablesEverything has a prior!Becomes this:

```
\pi \sim \text{Dirichlet}(\alpha)
For j = 1 to k do:
\mu_j \sim \text{Normal}(\mu_0, \Sigma_0)
\Sigma_j \sim \text{InvWishart}(\nu, \Psi)
```

```
For i = 1 to n do:

c_i \sim \text{Categorical}(\pi)

x_i \sim \text{Normal}(\mu_{c_i}, \Sigma_{c_i})
```

#### PDF

# First step in deriving an MCMC algorithm to learn this model: ▶ Get a PDF!

```
 \begin{aligned} \pi &\sim \text{Dirichlet}(\alpha) \\ \text{For } j &= 1 \text{ to } k \text{ do:} \\ \mu_j &\sim \text{Normal}(\mu_0, \Sigma_0) \\ \Sigma_j &\sim \text{InvWishart}(\nu, \Psi) \end{aligned}
```

```
For i = 1 to n do:

c_i \sim \text{Categorical}(\pi)

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Dirichlet $(\pi | \alpha) \times$  $\prod_{j} \operatorname{Normal}(\mu_{j} | \mu_{0}, \Sigma_{0}) \times \operatorname{InvWishart}(\Sigma_{j} | (\nu, \Psi) \times$   $\prod_{i} \operatorname{Categorical}(c_{i} | \pi) \times \operatorname{Normal}(x_{i} | \mu_{c_{i}}, \Sigma_{c_{i}})$ 

### Deriving a Gibbs Sampler

Initialize each unseen variable with an appropriate value

Then go through all of the variables cyclically

- $\triangleright$  Drop any part of the PDF that does not contain the variable in question
- $\triangleright$  And sample from the resulting function!

#### Update for Pi

 $\triangleright$  Start with the PDF:

Dirichlet $(\pi | \alpha) \times$  $\prod_{j} \operatorname{Normal}(\mu_{j} | \mu_{0}, \Sigma_{0}) \times \operatorname{InvWishart}(\Sigma_{j} | (\nu, \Psi) \times$   $\prod_{i} \operatorname{Categorical}(c_{i} | \pi) \times \operatorname{Normal}(x_{i} | \mu_{c_{i}}, \Sigma_{c_{i}})$ 

 $\triangleright$  Drop all terms without  $\pi$ :

$$\operatorname{Dirichlet}(\pi|\alpha) \times \prod_{i} \operatorname{Categorical}(c_i|\pi)$$

 $\triangleright$  How to sample from this??

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 $\operatorname{Dirichlet}(\pi|\alpha) \times \prod_{i} \operatorname{Categorical}(c_i|\pi)$ 

 $\triangleright$  How to sample from this??

- ▷ Easy! Wikipedia: Dirichlet is conjugate prior for Categorical!
- $\triangleright$  So use SciPy to generate the sample

#### Update for Component Means

 $\triangleright$  Start with the PDF:

Dirichlet $(\pi | \alpha) \times$  $\prod_{j} \operatorname{Normal}(\mu_{j} | \mu_{0}, \Sigma_{0}) \times \operatorname{InvWishart}(\Sigma_{j} | (\nu, \Psi) \times$   $\prod_{i} \operatorname{Categorical}(c_{i} | \pi) \times \operatorname{Normal}(x_{i} | \mu_{c_{i}}, \Sigma_{c_{i}})$ 

 $\triangleright$  Drop all terms without  $\mu_j$ :

Normal
$$(\mu_j | \mu_0, \Sigma_0) \times \prod_{i \text{ s.t. } c_i = j} \text{Normal}(x_i | \mu_j, \Sigma_j)$$

 $\triangleright$  How to sample from this??

▷ Easy! Wikipedia: MD Normal is conjugate prior for mean of MD Normal!

 $\triangleright$  So use SciPy to generate the sample

#### Update for Component Covars

 $\triangleright$  Start with the PDF:

Dirichlet $(\pi | \alpha) \times$  $\prod_{j} \operatorname{Normal}(\mu_{j} | \mu_{0}, \Sigma_{0}) \times \operatorname{InvWishart}(\Sigma_{j} | (\nu, \Psi) \times$   $\prod_{i} \operatorname{Categorical}(c_{i} | \pi) \times \operatorname{Normal}(x_{i} | \mu_{c_{i}}, \Sigma_{c_{i}})$ 

 $\triangleright$  Drop all terms without  $\Sigma_j$ :

InvWishart
$$(\Sigma_j | (\nu, \Psi) \times \prod_{i \text{ s.t. } c_i = j} \text{Normal}(x_i | \mu_j, \Sigma_j)$$

 $\triangleright$  How to sample from this??

- ▷ Easy! Wikipedia: InvWishart is conjugate prior for mean of MD Normal!
- $\triangleright$  So use SciPy to generate the sample

#### Final Algorithm

It is simply:

```
Initialize \pi, plus each c_i, \mu_j, \Sigma_j
For count = 1 to big do:
Update \pi
For j = 1 to j do:
Update \mu_j
Update \Sigma_j
For i = 1 to n do:
Update c_i
```

#### Final Remarks

We've gone thru learning for a GMM

- $\triangleright$  All other mixtures at least somewhat similar
- We've actually derived a Gibbs sampler for a GMM \*\*From Scratch\*\* ▷ Super cool!

Compare and contrast: Gibbs sampler vs. EM

## Questions?